## Bubbling Calabi-Yau geometry from matrix models

## Nick Halmagyi

Enrico Fermi Institute, University of Chicago,
Chicago, IL 60637, U.S.A.
E-mail: halmagyi@theory.uchicago.edu

## Takuya Okuda

Kavli Institute for Theoretical Physics, University of California, Santa Barbara, CA 93106, U.S.A.
E-mail: takuya@kitp.ucsb.edu

Abstract: We study bubbling geometry in topological string theory. Specifically, we analyse Chern-Simons theory on both the 3 -sphere and lens spaces in the presence of a Wilson loop of an arbitrary representation. For each three manifold, we formulate a multimatrix model whose partition function is the Wilson loop vev and compute the spectral curve. This spectral curve is closely related to the Calabi-Yau threefold which is the gravitational dual of the Wilson loop. Namely, it is the reduction to two dimensions of the mirror to the Calabi-Yau. For lens spaces the dual geometries are new. We comment on a similar matrix model relevant for Wilson loops in AdS/CFT.

Keywords: Chern-Simons Theories, Topological Strings, Gauge-gravity correspondence.

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## 1. Introduction and summary

A useful aspect of duality between a gauge theory and a gravitational system is the emergence of spacetime through dynamics of gauge theory. Deeper understanding of emergent geometry should help us find new formulations of string theory and quantum gravity that may be used to address fundamental questions in physics.

In gauge/gravity duality, the vacuum state corresponds to a certain background spacetime, and inserted operators to excitations. The fields of gauge theory backreact significantly to the insertion of some operators. The corresponding gravitational dual is a new geometry that shares the asymptotics with the original background. A bubble of new cycles supported by flux appears, and the new spacetime is thus called the bubbling geometry. The


Figure 1: The Young tableau $R$, shown rotated and inverted, is specified by the lengths $n_{I}$ and $k_{I}$ of the edges. Equivalently, $n_{I}$ and $k_{I}$ denote the lengths of the black and white regions that are obtained by vertically projecting down the edges in $R$ onto the horizontal line. $n_{m+1}$ is defined by $\sum_{I=1}^{m+1} n_{I}=N$.
bubbling phenomenon was originally found for local operators [1], and was generalized to Wilson loops [2-4] in AdS/CFT. It is useful to introduce a matrix model which captures the dynamics of all the relevant fields that respond to the operator insertion [7, 8]. One is able to visualize the backreaction in terms of eigenvalue distributions, which in turn encode the bubbling geometry on the gravity side.

The current work studies the topological string version of bubbling phenomena [5], which naturally extend the Gopakumar-Vafa gauge/gravity duality [6]|. More specifically we consider $\mathrm{U}(N)$ Chern-Simons theory on $S^{3}$ or lens space $L(p, 1)=S^{3} / \mathbb{Z}_{p}$ with Wilson loop insertions. The Wilson loop operator is defined as

$$
\begin{equation*}
W_{R} \equiv \operatorname{Tr}_{R} e^{\oint A} \tag{1.1}
\end{equation*}
$$

where $A$ is the gauge field and is integrated along the unknot. For $S^{3} / \mathbb{Z}_{p}$ we take the unknot that generates the fundamental group. The trace is evaluated in an arbitrary representation $R$ of $\mathrm{U}(N)$. Throughout the paper the symbol $R$ also denotes the corresponding Young tableau, and we parametrize it as in figure1. Each edge length be it $n_{I}$ or $k_{I}$, will correspond to the size of a new cycle in the bubbling geometry.

Building on the earlier work 9, 10], we formulate a matrix model whose partition function is the vev of the Wilson loop in $S^{3}$ or $S^{3} / \mathbb{Z}_{p}$. We then study the eigenvalue dynamics in the large $N$ limit and derive the spectral curve. For $S^{3}$ the spectral curve is precisely the mirror of the bubbling toric Calabi-Yau geometry identified as the gravitational dual of the Wilson loop in [5]. The topology of this threefold depends on the data encoded in the Young tableau $R$ : its toric web diagram is shown in figure 2 (a)

For the lens spaces $S^{3} / \mathbb{Z}_{p}$, the backreaction of the fields to the Wilson loop leads to additional classical vacua, and the path-integral splits into sectors corresponding to the different vacua. Because the matrix model we formulate computes the Wilson loop vev in each sector, we propose that for given $N, p$, and $R$, a single Wilson loop insertion is dual to a sum over bubbling geometries. Each term in the sum is the toric Calabi-Yau that is


Figure 2: (a) The toric web diagram for the bubbling Calabi-Yau dual to the Wilson loop $W_{R}$ in $S^{3}$. It has $2 m+1$ copies of $\mathbf{P}^{1}$. (b) The web diagram for the bubbling Calabi-Yau dual to $W_{R}$ in lens space $S^{3} / \mathbb{Z}_{p}$ with $p=3$. The diagram is a chain of $m+1$ basic units.
mirror to the spectral curve which we derive. The summed geometries have the same toric data shown in figure 2(b) ${ }^{1}$ except different values of Kähler moduli. As in the $S^{3}$ case, the topology of the geometry depends on the Young tableau data.

The paper is organized as follows. Section 2 focuses on the $S^{3}$ case. In subsection 2.1 we present the matrix model for a Wilson loop in $S^{3}$. In subsection 2.2 we derive the matrix model from physical arguments. Specifically we present it as an open string field theory of a D-brane configuration that realizes the Wilson loop. Then we algebraically derive the matrix model in subsection 2.3. In subsection 2.4, we solve the matrix model in the large $N$ limit and derive the spectral curve, which is the mirror of the bubbling Calabi-Yau found in (5).

Section 3 deals with lens space $S^{3} / \mathbb{Z}_{p}$, and is structured in parallel with section 2. For each vacuum of the gauge theory with Wilson loop insertion, we derive the spectral curve. We propose that the mirror toric Calabi-Yau is the bubbling geometry dual to the Wilson loop.

Appendix Asummarizes the notation regarding the Young tableau data. In appendix we study alternative matrix models that compute the Wilson loop vev. The models are the direct analog of the matrix models for $\mathcal{N}=4$ Yang-Mills considered in 11. Appendix $D$ is targeted at readers interested in AdS/CFT. We use the algebraic techniques in subsection 2.3 to formulate a matrix model, whose partition function is the vev of the supersymmetric circular Wilson loop in $\mathcal{N}=4$ Yang-Mills. In this formulation it is very easy to derive the eigenvalue distributions for the Wilson loop found in [11-14.

## 2. Bubbling Calabi-Yau for $S^{3}$ from a matrix model

### 2.1 Matrix model for a Wilson loop in $S^{3}$

The realization that the open topological A-model can be reduced to a matrix model first appeared in Marino's work [6], and a B-model version of this idea was subsequently derived by Dijkgraaf and Vafa 15]. Both derivations are of course mirror to each other as was demonstrated for certain examples in the nice work 10]. We are interested here

[^0]in the A-model, which is of course equivalent to Chern-Simons theory [16], possibly with instanton corrections 16-18.

Marino's observation for Chern-Simons theory on $S^{3}$ with the gauge group $G$ was that the partition function is

$$
\begin{align*}
\mathcal{Z} & =\int d_{H} u e^{-\frac{1}{2 g_{s}} \operatorname{Tr} u^{2}} \\
& =\int \frac{1}{N!} \prod_{i=1}^{N} d u_{i} \prod_{i<j}\left(2 \sinh \frac{u_{i}-u_{j}}{2}\right)^{2} e^{-\frac{1}{2 g_{s}} \sum_{i} u_{i}^{2}} \tag{2.1}
\end{align*}
$$

where the topological string coupling constant $g_{s}$ is identified with the Chern-Simons coupling constant, $U=e^{u}$, and $d_{H} u$ is the Haar measure on $G$ with unusual integration range. On the second line we specialized to the case $G=\mathrm{U}(N)$, and each $u_{i}$ is integrated from $-\infty$ to $+\infty$. This observation by itself may not be overwhelming since it is a reformulation of Witten's classic result for the partition function 19. The main utility is the generalization to different manifolds, where they carry topological data [9, 10, 20, 21] and to Wilson loops which we describe in the current work.

One very interesting feature of (2.1) however is that it secretly knows about the geometric transition of Gopakumar and Vafa [6]. While Chern-Simons theory is equivalent to the open A-model on the deformed conifold, the spectral curve of (2.1) is directly related to the resolved conifold. If the Calabi-Yau threefold mirror to the resolved conifold is defined by the equation $x y=f\left(e^{u}, e^{v}\right)$, the spectral curve is then given by $f\left(e^{u}, e^{v}\right)=0$. The orientifold case was worked out in [22. Our main interest in this paper is to generalize this aspect to include the insertion of Wilson loop operators. Wilson loops in the topological gauge/gravity duality have been considered before by Ooguri and Vafa 23]. The current work and the previous work [5, 24, 25] extends this in two ways. Firstly, the full backreaction of the Wilson loop is taken into account, as explained in 24 this means the Wilson loop vev can be expressed in terms of purely closed string enumerative invariants. Secondly we provide a dictionary for a single Wilson loop in a particular representation $R$, whereas in [23] a sum of Wilson loop insertions was considered where the summation is over representations.

Wilson loop operators

$$
\begin{equation*}
W_{R}=\operatorname{Tr} P e^{\oint A} \tag{2.2}
\end{equation*}
$$

are specified by two pieces of data: the representation $R$ of the gauge group $G$ and a curve $\gamma$ in $M$ which the gauge field is integrated over. We will be considering all representations of $\mathrm{U}(N)$ such that the $n_{I}$ and $k_{I}$ in figure 1 are large and our $\gamma$ will be the unknot.

The relation between Chern-Simons theory and the matrix model was extended to include Wilson loops in [10]:

$$
\begin{equation*}
\left\langle W_{R}\right\rangle=\int d_{H} u e^{-\frac{1}{2 g_{s}} \operatorname{Tr}\left(u^{2}\right)} \operatorname{Tr}_{R} e^{u} \tag{2.3}
\end{equation*}
$$

We will show that the vev of the Wilson loop is in fact the partition function of the following matrix model:

$$
\begin{align*}
\left\langle W_{R}\right\rangle= & \int \prod_{I=1}^{m+1} d_{H} u^{(I)} e^{-\frac{1}{2 g_{s}} \operatorname{Tr} u^{(I) 2}} e^{L_{I} \operatorname{Tr} u^{(I)}} \prod_{I<J} \operatorname{det}\left(e^{u^{(I)} / 2} \otimes e^{-u^{(J)} / 2}-e^{-u^{(I)} / 2} \otimes e^{u^{(J)} / 2}\right) \\
=\int & \prod_{I}\left(\frac{1}{n_{I}!} \prod_{i} d u_{i}^{(I)} \prod_{i<j}\left(2 \sinh \frac{u_{i}^{(I)}-u_{j}^{(I)}}{2}\right)^{2} e^{-\frac{1}{2 g_{s}} \sum_{i}\left(u_{i}^{(I)}\right)^{2}} e^{L_{I} \sum_{i} u_{i}^{(I)}}\right) \\
& \times \prod_{I<J} \prod_{i, j}\left(2 \sinh \frac{u_{i}^{(I)}-u_{j}^{(J)}}{2}\right), \tag{2.4}
\end{align*}
$$

with

$$
\begin{equation*}
L_{I} \equiv \sum_{J=I}^{m} k_{J}-\frac{1}{2} \sum_{J=1}^{I-1} n_{J}+\frac{1}{2} \sum_{J=I+1}^{m+1} n_{J} \quad \text { for } I=1, \ldots, m+1 \tag{2.5}
\end{equation*}
$$

This is a Gaussian $(m+1)$-matrix model with certain interactions which in the next section we explain from the target space viewpoint.

### 2.2 Physical derivation of the matrix model

In this subsection we derive the matrix model (2.4) as the world-volume theory in a D-brane configuration that is equivalent to the Wilson loop insertion. Further geometric transition of the branes leads to the purely closed string geometry in figure 2 (a), and the three steps are summarized in figure 8 . As we will describe, the essential details in each step can be found in the earlier work [5, 24, 25].

We start with the deformed conifold geometry given by the equation

$$
\begin{equation*}
z_{1} z_{2}=w=z_{3} z_{4}+\mu, \quad z_{i}, w \in \mathbb{C} \tag{2.6}
\end{equation*}
$$

where $\mu$ is the complex structure parameter that we take to be real positive. The geometry has the structure of $T^{2} \times \mathbb{R}$ fibration over $\mathbb{R}^{3}$. Let us denote the basis cycles of $T^{2}$ by $\alpha$ and $\beta$. In the base $\mathbb{R}^{3}, \alpha$ degenerates along one line and $\beta$ degenerates on another. The minimal $S^{3}$ is obtained by fibering this $T^{2}$ along a line interval that connects the two loci.

We wrap $N$ branes on $M=S^{3}$ thus engineering the $\mathrm{U}(N)$ Chern-Simons theory. In addition we place a stack of $P$ branes $^{2}$ wrapping a non-compact three cycle $L$ of topology $\mathbb{R}^{2} \times S^{1}$. The cycle $L$ intersects $M$ along a circle that is identified with $\alpha$. These branes were introduced in [23] where the partition function obtained after integrating out the bifundamental $M-L$ strings was shown to be a generating function for Wilson loop vevs. The generating function is a summation over representations of $\mathrm{U}(N)$ and the $S^{1}$ common to $M$ and $L$ is the defining curve of the Wilson loop. Since $L$ is non-compact one should enforce a boundary condition at infinity for the gauge field on the stack of branes which wrap $L$. In [23] this was implicitly done by fixing the background holonomy of the gauge field along $\alpha$.

[^1]

Figure 3: (a) The web diagram for the deformed conifold. $\alpha$ and $\beta$ degenerate along the horizontal and vertical lines respectively. The dashed line represents $S^{3}$ that $N$ D-branes wrap. The other dashed line ending on the vertical solid line represents a non-compact cycle $L=\mathbb{R}^{2} \times S^{1}$ that $P$ non-compact D-branes wrap. (b) $P$ non-compact branes are distributed along the horizontal line where $\alpha$ degenerates.

A different boundary condition isolates a single Wilson loop in the representation $R$ 24. So this brane construction is equivalent to the Wilson loop insertion. See figure 3(a). This boundary condition is equivalent to the gauge field having a nontrivial holonomy matrix along the $\beta$ cycle which encodes the data of $R$.

First, the above brane configuration is equivalent to another system that has a new set of non-compact D-branes, distributed along the locus where $\alpha$ degenerates [25]. The new system has only $N-P\left(=n_{m+1}\right)$ D-branes wrapping the $S^{3}$. As we review in appendix B, a stack of $n_{I}$ non-compact branes sits at distance $a_{I}=g_{s}\left(L_{I}-L_{m+1}\right)$ away from the $S^{3}$ for $I=1, \ldots, m$. See figure 3 (b).

Second, by considering the new ambient geometry of figure 3(c) with more complex structure moduli given by

$$
\begin{equation*}
z_{1} z_{2}=w, \quad z_{3} z_{4}=(\mu-w) \prod_{I=1}^{m}\left(1-w / \mu_{I}\right) \tag{2.7}
\end{equation*}
$$

the non-compact branes can be compactified without changing the physics. This is a legitimate maneuver since it reduces to the deformed conifold (2.6) by making the complex structure moduli $\mu_{I}$ infinite and A-model depends only on Kähler moduli. The result is the D-brane system from which we can derive the matrix model (2.4).

We now have a daisy chain of Chern-Simons theories all of them on an $S^{3}$ and there are then annulus instantons which connect them [18]. The representation $R$ of the Wilson loop determines all the necessary data, in particular the $I$-th Chern-Simons theory has gauge group $\mathrm{U}\left(n_{I}\right), I=1, \ldots, m+1$. We get annulus instantons by integrating out the massive bifundamental open strings 23. Since the mass of the string between the $I$-th and the $J$-th spheres is $a_{I}-a_{J}$, the interactions generated from such annulus instantons are summarized as

$$
\begin{equation*}
\left\langle W_{R}\right\rangle \sim \int \prod_{I=1}^{m+1}\left[D A_{I}\right] e^{i S_{\mathrm{CS}}\left(A_{I}\right)} \prod_{I<J} \operatorname{det}\left(e^{\frac{1}{2}\left(a_{I}-a_{J}\right)} U_{I}^{\frac{1}{2}} \otimes U_{J}^{-\frac{1}{2}}-e^{\frac{1}{2}\left(a_{J}-a_{I}\right)} U_{I}^{-\frac{1}{2}} \otimes U_{J}^{\frac{1}{2}}\right) \tag{2.8}
\end{equation*}
$$

where $S_{\mathrm{CS}}$ is the Chern-Simons action, and $U_{I} \equiv P \exp \oint_{\alpha} A_{I}$ is the holonomy along the unknot in the $I$-th $S^{3}$. Given this field theory description, we can now reduce it to a matrix
model (10]:

$$
\begin{equation*}
\left\langle W_{R}\right\rangle \sim \int \prod_{I=1}^{m+1} d_{H} u^{(I)} e^{-\frac{1}{2 g_{s}} \operatorname{Tr}\left(u^{(I)}\right)^{2}} \prod_{I<J} \operatorname{det}\left(2 \sinh \frac{\left(a_{I}+u^{(I)}\right) \otimes 1-1 \otimes\left(a_{J}+u^{(J)}\right)}{2}\right) . \tag{2.9}
\end{equation*}
$$

By redefining $u^{(I)} \rightarrow u^{(I)}-g_{s} L_{I}=u^{(I)}-a_{I}+(I$-independent), we finally obtain (2.4). It is a nontrivial consistency check that the physical derivation here gives the values of holonomy $a_{I}$ that we need to agree with the algebraic derivation in the next subsection.

Third and finally, we can go one step further in the target space analysis though we have completed our task in this subsection, When each $S^{3}$ in figure 3(c) undergoes a conifold transition the resulting closed string geometry is the toric Calabi-Yau manifold whose web diagram is shown in figure 2(a). This is the Calabi-Yau manifold which is referred to as the bubbling geometry [5]. We will see in subsection 2.4 that the eigenvalue dynamics in the matrix model demonstrates the geometric transition.

### 2.3 Algebraic derivation of the matrix model

We now provide an algebraic derivation of (2.4). Our starting point is (2.3). Using a standard formula for the character of $\mathrm{U}(N)$ this can be written as

$$
\begin{equation*}
\left\langle W_{R}\right\rangle=\int \frac{1}{N!} \prod_{i} d u_{i} \prod_{i<j}\left(2 \sinh \frac{u_{i}-u_{j}}{2}\right)^{2} e^{-\frac{1}{2 g_{s}} \sum u_{i}^{2}} \frac{\operatorname{det}\left(e^{\left(N+R_{j}-j\right) u_{i}}\right)}{\operatorname{det}\left(e^{(N-j) u_{i}}\right)}, \tag{2.10}
\end{equation*}
$$

where $R_{j}$ is as usual the number of boxes in the $j$-th row of $R$. Now we expand this ratio of determinants into something more compatible with the matrix model:

$$
\begin{align*}
\frac{\operatorname{det}\left(e^{\left(N+R_{j}-j\right) u_{i}}\right)}{\operatorname{det}\left(e^{(N-j) u_{i}}\right)} & =\sum_{\sigma \in \mathcal{S}_{N}} \operatorname{sgn}(\sigma) \prod_{i} e^{\left(N+R_{i}-i\right) u_{\sigma(i)}} / \prod_{i<j}\left(e^{u_{i}}-e^{u_{j}}\right) \\
& =\sum_{\sigma \in \mathcal{S}_{N}} \prod_{i} e^{\left(N+R_{i}-i\right) u_{\sigma(i)}} / \prod_{i<j}\left(e^{u_{\sigma(i)}}-e^{\left.u_{\sigma(j)}\right)} .\right. \tag{2.11}
\end{align*}
$$

Since $u_{i}$ are dummy variables the summation over the permutation group $\mathcal{S}_{N}$ produces $N$ ! identical terms, so we can write

$$
\left\langle W_{R}\right\rangle=\int \prod_{i} d u_{i} \prod_{i<j}\left(2 \sinh \frac{u_{i}-u_{j}}{2}\right)^{2} e^{-\frac{1}{2 g_{s}} \sum u_{i}^{2}} \prod_{i} e^{\left(N+R_{i}-i\right) u_{i}} / \prod_{i<j}\left(e^{u_{i}}-e^{u_{j}}\right) .
$$

At this point the Wilson loop insertion has been recast into a linear term in the exponential and a certain denominator term. There will be partial cancellation of this denominator term against the measure and also against the linear term. We relabel the variables as

$$
\left(u_{1}, \ldots, u_{N}\right)=\left(u_{1}^{(1)}, \ldots, u_{n_{1}}^{(1)}, u_{1}^{(2)}, \ldots, u_{n_{2}}^{(2)}, \ldots, u_{1}^{(m+1)}, \ldots, u_{n_{m+1}}^{(m+1)}\right)
$$

where we recall that the Young tableau $R$ has $m$ blocks of rows. Then

$$
\begin{aligned}
\left\langle W_{R}\right\rangle=\int & \prod_{I=1}^{m+1} \\
& \prod_{i=1}^{n_{I}} d u_{i}^{(I)} \prod_{I} \prod_{i<j}\left(2 \sinh \frac{u_{i}^{(I)}-u_{j}^{(I)}}{2}\right)^{-\frac{1}{2 g_{s}} \sum_{I, i}\left(u_{i}^{(I)}\right)^{2}} \prod_{I<J} \prod_{i, j}\left(2 \sinh \frac{u_{i}^{(I)}-u_{j}^{(J)}}{2}\right)^{\left(N+K_{I}-\left(N_{m-I+2+i)) u_{i}^{(I)}}^{2}\right.\right.} \\
& \times\left(\prod_{I} \prod_{i<j}\left(e^{u_{i}^{(I)}}-e^{u_{j}^{(I)}}\right) \prod_{I<J} \prod_{i, j}\left(e^{u_{i}^{(I)}}-e^{u_{j}^{(J)}}\right)\right)^{-1}
\end{aligned}
$$

The integers $K_{I}$ and $N_{I}$ are defined in appendix A. This can be further simplified, using the trivial fact that integration variables are dummy variables, to

$$
\begin{align*}
\left\langle W_{R}\right\rangle= & \int \prod_{I=1}^{m+1}\left(\frac{1}{n_{I}!} \prod_{i} d u_{i}^{(I)} \prod_{i<j}\left(2 \sinh \frac{u_{i}^{(I)}-u_{j}^{(I)}}{2}\right)^{2} e^{-\frac{1}{2 g_{s}} \sum_{i}\left(u_{i}^{(I)}\right)^{2}} e^{\left(N+K_{I}-N_{m-I+2}-n_{I}\right) \sum_{i} u_{i}^{(I)}}\right. \\
& \left.\times \sum_{\sigma_{I} \in S_{n_{I}}} e^{\sum_{i}\left(n_{I}-i\right) u_{\sigma_{I}(i)}^{(I)}} \prod_{i<j}\left(e^{u_{\sigma_{I}(i)}^{(I)}}-e^{u_{\sigma_{I}(j)}^{(I)}}\right)\right) \prod_{I<J} \prod_{i, j} \frac{\left(2 \sinh \frac{u_{i}^{(I)}-u_{j}^{(J)}}{2}\right)^{2}}{e^{u_{i}^{(I)}}-e^{u_{j}^{(J)}}} \\
= & \int \prod_{I=1}^{m+1}\left(\frac{1}{n_{I}!} \prod_{i} d u_{i}^{(I)} \prod_{i<j}\left(2 \sinh \frac{u_{i}^{(I)}-u_{j}^{(I)}}{2}\right)^{2} e^{\left.-\frac{1}{2 g_{s} \sum_{i}\left(u_{i}^{(I)}\right)^{2}} e^{K_{I} \sum_{i} u_{i}^{(I)}}\right)}\right. \\
& \times \prod_{I<J} \prod_{i, j} \frac{\left(2 \sinh \frac{u_{i}^{(I)}-u_{j}^{(J)}}{2}\right)^{2}}{1-e^{u_{j}^{(J)}-u_{i}^{(I)}}} \\
=\int & \prod_{I=1}^{m+1}\left(\frac{1}{n_{I}!} \prod_{i} d u_{i}^{(I)} \prod_{i<j}\left(2 \sinh \frac{u_{i}^{(I)}-u_{j}^{(I)}}{2}\right)^{2} e^{-\frac{1}{2 g_{s}} \sum_{i}\left(u_{i}^{(I)}\right)^{2}} e^{L_{I} \sum_{i} u_{i}^{(I)}}\right) \\
& \times \prod_{I<J} \prod_{i, j}\left(2 \sinh \frac{u_{i}^{(I)}-u_{j}^{(J)}}{2}\right), \tag{2.12}
\end{align*}
$$

where $L_{I}$ are defined in (2.5) and we have use the relations

$$
\begin{align*}
\prod_{I<J} \prod_{i, j}\left(2 \sinh \frac{u_{i}^{(I)}-u_{j}^{(J)}}{2}\right)^{2} & =e^{\sum_{I}\left(n_{I}-N\right) \sum_{i} u_{i}^{(I)}} \prod_{I<J} \prod_{i, j}\left(e^{u_{i}^{(I)}}-e^{u_{j}^{(J)}}\right)^{2}, \\
\prod_{I<J} \prod_{i, j}\left(e^{u_{i}^{(I)}}-e^{u_{j}^{(J)}}\right) & =e^{\sum_{I}\left(N-N_{m-I+1}\right) \sum_{i} u_{i}^{(I)}} \prod_{I<J} \prod_{i, j}\left(1-e^{u_{j}^{(J)}-u_{i}^{(I)}}\right) . \tag{2.13}
\end{align*}
$$

At this point we essentially have an $m$-matrix model with interactions between the matrices given by the last line in (2.12).

### 2.4 Spectral curve as the bubbling geometry dual to a Wilson loop in $S^{3}$

Matrix models have an associated geometry called the spectral curve. One can think of $\left\langle W_{R}\right\rangle$ as a single Gaussian matrix model with somewhat complicated insertion, or alterna-
tively as we have demonstrated, as an $m$-matrix model with certain simpler interactions. Taking the latter point of view, we now derive the spectral curve and explain its string theory interpretation.

The equations of motion for $u_{i}^{(I)}$ are

$$
\begin{equation*}
0=-u_{i}^{(I)}+g_{s} L_{I}+g_{s} \sum_{j \neq i} \operatorname{coth} \frac{u_{i}^{(I)}-u_{j}^{(I)}}{2}+\frac{1}{2} g_{s} \sum_{J \neq I, i, j} \operatorname{coth} \frac{u_{i}^{(I)}-u_{j}^{(J)}}{2} \tag{2.14}
\end{equation*}
$$

To solve them we define the resolvents ${ }^{3}$

$$
\begin{equation*}
v^{(I)}(z)=g_{s} \sum_{i=1}^{n_{I}} \frac{e^{u_{i}^{(I)}}}{e^{u_{i}^{(I)}}-e^{z}}, \quad v(z)=\sum_{I=1}^{m+1} v^{(I)}(z) \tag{2.15}
\end{equation*}
$$

We now assume that the eigenvalues distribute themselves into $m$ distinct cuts along the real axis, then write $(\overline{2.14})$ an equation on the $I$-th cut:

$$
\begin{equation*}
z+v_{+}^{(I)}(z)+v_{-}^{(I)}(z)+\sum_{J \neq I} v^{(J)}(z)=g_{s}\left(\sum_{J=I}^{m} k_{J}+\sum_{J=I}^{m+1} n_{J}\right) \tag{2.16}
\end{equation*}
$$

where $v_{+}^{(I)}(z)$ and $v_{-}^{(I)}(z)$ are the values of $v^{(I)}(z)$ just above and below the cut, respectively. It will be convenient to rewrite this as

$$
\begin{equation*}
z+v_{ \pm}(z)=-v_{\mp}^{(I)}(z)+g_{s}\left(\sum_{J=I}^{m} k_{J}+\sum_{J=I}^{m+1} n_{J}\right) \tag{2.17}
\end{equation*}
$$

To derive the spectral curve, we generalize the complex analysis technique used in 26 to solve the Chern-Simons matrix model for $S^{3} / \mathbb{Z}_{p}$. The crucial step in solving this model is to find a set of functions of the resolvents $v^{(I)}$ which are regular on the whole $Z$-plane where $Z=e^{z}$ is of course $\mathbb{C}^{*}$ valued. Then the asymptotics of $v^{(I)}$ will allow us to fix these functions exactly and finally extract the equation for the spectral curve. The technical reason that we will be able to solve this model exactly is that the interaction terms in the equation of motion can be written polynomially in terms of the resolvents. This is not the case for the related $\mathcal{N}=4$ Yang Mills matrix models described in appendix $D$ and also in 11 .

We first define some new quantities

$$
\begin{align*}
& X_{0}(Z)=Z e^{v} \\
& X_{I}(Z)=A_{I} e^{-v^{(I)}}, \quad I=1, \ldots, m+1 \tag{2.18}
\end{align*}
$$

where $Z=e^{z}$ and $A_{I}=\exp g_{s}\left(\sum_{J=I}^{m} k_{J}+\sum_{J=I}^{m+1} n_{J}\right)$. Equation (2.17) implies that $X_{0}$ and $X_{I}$ are exchanged as one goes through the $I$-th cut, leaving any symmetric polynomial of $\left(X_{0}, X_{1}, \ldots, X_{m+1}\right)$ invariant under the process. The symmetric polynomial is regular

[^2]on all of the cuts, and the only singularities are at $Z=\infty$. Let us now recall the definition of the $j$-th elementary symmetric polynomials $E_{j}$ :
\[

$$
\begin{equation*}
E_{j}\left(x_{1}, \ldots, x_{n}\right)=\sum_{i_{1}<\cdots<i_{j}} x_{i_{1}} \ldots x_{i_{j}} \tag{2.19}
\end{equation*}
$$

\]

Together with the definition (2.15) of the resolvents, the asymptotics as $z \rightarrow \pm \infty$ determine the $E_{j}\left(X_{0}, \ldots, X_{m+1}\right)$ exactly in terms of Young tableau data:

$$
\begin{align*}
E_{0}\left(X_{0}, \ldots, X_{m+1}\right) & =1, \\
E_{j}\left(X_{0}, \ldots, X_{m+1}\right) & =a_{j, 0}+a_{j, 1} Z \quad \text { for } j=1, \ldots, m+1,  \tag{2.20}\\
E_{m+2}\left(X_{0}, \ldots, X_{m+1}\right) & =A_{1} \ldots A_{m+1} Z .
\end{align*}
$$

The coefficients are given by

$$
\begin{align*}
& a_{j, 0}=\sum_{1 \leq J_{1}<\cdots<J_{j} \leq m+1} B_{J_{1}} \ldots B_{J_{j}} \quad \text { for } \quad j=1, \ldots, m+1, \\
& a_{j, 1}=\sum_{1 \leq J_{1}<\cdots<J_{j-1} \leq m+1} A_{J_{1}} \ldots A_{J_{j-1}} \quad \text { for } \quad j=2, \ldots, m+1, \quad a_{1,1} \equiv 1, \tag{2.21}
\end{align*}
$$

where we introduced $B_{I}=\exp g_{s}\left(\sum_{J=I}^{m} k_{J}+\sum_{J=I+1}^{m+1} n_{J}\right)$.
In fact the $E_{j}$ appear as the coefficients of $Y^{j}$ in the expansion of the function

$$
\begin{align*}
f(Y, Z) & \equiv \prod_{J=0}^{m+1}\left(Y-X_{J}(Z)\right) \\
& =\sum_{j=0}^{m+2}(-)^{j} Y^{m+2-j} E_{j}\left(X_{0}, \ldots, X_{m+1}\right) \\
& =Y^{m+2}+\sum_{j=1}^{m+1}(-1)^{j} Y^{m+2-j}\left(a_{j, 0}+a_{j, 1} Z\right)+(-1)^{m_{2}} A_{1} \ldots A_{m+1} Z, \tag{2.22}
\end{align*}
$$

and this vanishes upon substituting $X_{I}$ for $Y$. So we arrive at an equation for the spectral curve of the matrix model (2.4):

$$
\begin{equation*}
f(Y, Z)=0, \tag{2.23}
\end{equation*}
$$

where $(Y, Z)$ are $\mathbb{C}^{*}$ valued variables.
Since $f(Y, Z)$ is of degree $m+2$ in $Y$, the spectral curve is obtained by gluing $m+2$ cylindrical sheets. In particular (2.23) is satisfied by the total resolvent $v(z)$ through substitution $Y=X_{0} \equiv e^{z+v}$, and the sheet on which $v(z)$ is naturally defined has $m+1$ cuts. By going through the $I$-th cut $(I=1, \ldots, m+1)$, one moves to the $I$-th sheet as $v(z)$ changes to $-z-v^{(I)}+$ const. See figure (7).

This Riemann surface is related to a Calabi-Yau threefold in a way which is by now well known, namely the threefold is given by

$$
\begin{equation*}
w x=f(Y, Z) \tag{2.24}
\end{equation*}
$$


(a)

(b)

Figure 4: (a) The spectral curve is constructed by gluing one sheet to $m+1$ other sheets through $m+1$ cuts. Each sheet is a cylinder parametrized by $z$ with identification $z \sim z+2 \pi i$. Compare with figure 2(a). (b) The vertices plot the monomials $Y^{a} Z^{b}$ appearing in the equation (2.23) for the spectral curve. By connecting the vertices by suitable edges, one obtains a graph that is dual to the toric web for the bubbling geometry shown in figure 2(a).
where $w, x$ are $\mathbb{C}$ valued. It is a feature of the mirror symmetry work of Hori-Vafa [27] that we can write down the toric fan directly from the Riemann surface data above. The recipe is to insert a vertex $(a, b)$ on the integral 2-dimensional lattice for each monomial $Y^{a} Z^{b}$ appearing in (2.23). By connecting the vertices with suitable edges ${ }^{4}$ one obtains a graph, and the three-dimensional cone over this graph is the toric fan of the bubbling Calabi-Yau. The two dimensional graph is the dual graph of the toric web diagram, so from figure 4 (b) we see agreement with the previous work [5].

For concreteness we now work out the simplest case when $R$ is a rectangle. In this case the nontrivial data is

$$
\begin{array}{ll}
A_{1}=e^{t_{1}+t_{2}+t_{3}}, & A_{2}=e^{t_{3}} \\
B_{1}=e^{t_{2}+t_{3}}, & B_{2}=1
\end{array}
$$

and

$$
\begin{array}{ll}
a_{1,0}=1+e^{t_{2}+t_{3}}, & a_{1,1}=1 \\
a_{2,0}=e^{t_{2}+t_{3}}, & a_{2,1}=e^{t_{1}+t_{2}+t_{3}}+e^{t_{3}}  \tag{2.26}\\
a_{3,0}=0, & a_{3,1}=e^{t_{1}+t_{2}+2 t_{3}}
\end{array}
$$

with $t_{1}=g_{s} n_{1}, t_{2}=g_{s} k_{1}, t_{3}=g_{s} n_{2}$, and so the spectral curve is explicitly given by

$$
\begin{equation*}
Y^{3}-\left(1+e^{t_{2}+t_{3}}\right) Y^{2}-Y^{2} Z+e^{t_{2}+t_{3}} Y+\left(e^{t_{1}+t_{2}+t_{3}}+e^{t_{3}}\right) Y Z-e^{t_{1}+t_{2}+2 t_{3}} Z=0 \tag{2.27}
\end{equation*}
$$

[^3]

Figure 5: The eigenvalues are distributed along $m+1$ cuts on the cylinder parametrized by $z$.

### 2.5 Eigenvalue distribution

The exact eigenvalue distribution can be obtained by solving ( 2.23 ) for $v(z)$ via $Y=$ $\exp (z+v)$ and by computing the eigenvalue density $\rho \propto v_{+}(z)-v_{-}(z)$ along the cuts. Here we apply force balance to derive the approximate distribution when

$$
\begin{equation*}
g_{s} n_{I} \gg 1, \quad g_{s} k_{I} \gg 1 \quad \text { for all } I . \tag{2.28}
\end{equation*}
$$

Force balance is easier to understand intuitively.
We make the assumption, to be justified a posteriori, that

$$
\begin{equation*}
u_{i}^{(I)}-u_{j}^{(J)} \gg 1 \text { for all } I, J, i, j \text { such that } I<J . \tag{2.29}
\end{equation*}
$$

Because the last term in (2.14) becomes constant we have

$$
\begin{equation*}
u_{i}^{(I)}=g_{s} \sum_{j \neq i} \frac{2}{1-e^{u_{j}^{(I)}-u_{i}^{(I)}}}+g_{s}\left(\sum_{J=1}^{m} k_{J}-\sum_{J=1}^{I} n_{J}+\sum_{J=I+1}^{m+1} n_{J}\right) . \tag{2.30}
\end{equation*}
$$

We expect that when $g_{s} n_{I}$ is large, the eigenvalues of $u^{(I)}$ spread over a large region, allowing us to approximate the function $1 /\left(1-e^{x}\right)$ in (2.30) by a step function. If we order the eigenvalues so that $u_{i}^{(I)}<u_{j}^{(I)}$ for any $i<j$, it follows that

$$
\begin{equation*}
u_{i}^{(I)}=2 g_{s} i+g_{s}\left(\sum_{J=1}^{m} k_{J}-\sum_{J=1}^{I} n_{J}+\sum_{J=I+1}^{m+1} n_{J}\right), \quad i=1, \ldots, n_{I} . \tag{2.31}
\end{equation*}
$$

Along the $I$-th cut that has width $2 g_{s} n_{I}$, the eigenvalues of $u^{(I)}$ are distributed uniformly. The $I$-th and $I+1$ cuts are distance $g_{s} k_{I}$ apart from each other. ${ }^{5}$ We can thus justify the approximations above when $g_{s} n_{I}$ and $g_{s} k_{I}$ are all large. See figure 5 . As discussed above, this sheet is connected to other $m+1$ sheets through the $m+1$ cuts as shown in figure $7_{\text {(a) }}$ (a).

## 3. Bubbling Calabi-Yau for lens space from a matrix model

### 3.1 Matrix model for a Wilson loop in lens space

A simple generalization of the topological A-model on $T^{*} S^{3}$ is the orbifold $X_{p} \equiv$ $T^{*}\left(S^{3} / \mathbb{Z}_{p}\right)$ [10]. The particular orbifold action is such that $S^{3} / \mathbb{Z}_{p}$ is the lens space $L(p, 1)$.

[^4]This space is defined by the equation

$$
\begin{equation*}
\left|z_{1}\right|^{2}+\left|z_{2}\right|^{2}=1 \tag{3.1}
\end{equation*}
$$

for complex variables $z_{1}$ and $z_{2}$, together with identification

$$
\begin{equation*}
\left(z_{1}, z_{2}\right) \sim\left(e^{2 \pi i / p} z_{1}, e^{-2 \pi i / p} z_{2}\right) . \tag{3.2}
\end{equation*}
$$

We study the Wilson loop

$$
\begin{equation*}
W_{R}=\operatorname{Tr}_{R} P e^{\oint A} \tag{3.3}
\end{equation*}
$$

along a circle that is the generator of the fundamental group. We assume that the circle is the unknot.

The $\mathrm{U}(N)$ Chern-Simons theory on $L(p, 1)$ has many vacua. Since the equation of motion is solved by a flat connection, the vacua are in one-to-one correspondence with the $N$-dimensional representations of $\pi_{1}\left(S^{3} / \mathbb{Z}_{p}\right)=\mathbb{Z}_{p}$. The group $\mathbb{Z}_{p}$ is abelian, so any such representation is a sum of one-dimensional ones. A one-dimensional representation is specified by an integer $a=1, \ldots, p$. Thus a vacuum is specified by a partition of $N$ :

$$
\begin{equation*}
N=N_{1}+N_{2}+\cdots+N_{p} . \tag{3.4}
\end{equation*}
$$

Here $N_{a}$ is the number of times the $a$-th irrep appears. The contribution of this vacuum to the partition function is given by

$$
\begin{equation*}
\mathcal{Z}_{p}=\int \prod_{i=1}^{N} d u_{i} \prod_{i<j}\left(2 \sinh \frac{u_{i}-u_{j}}{2}\right)^{2} \exp \left(-\frac{p}{2 g_{s}} \sum_{i} u_{i}^{2}+\frac{2 \pi i}{g_{s}} \sum n_{i} u_{i}\right) \tag{3.5}
\end{equation*}
$$

This matrix model was formulated in [9], and was studied for example in [10, 26, 29, [3].
According to the prescription in [10] (see also [31), the contribution from this vacuum to the Wilson loop vev is given by

$$
\begin{equation*}
\left\langle W_{R}\right\rangle_{p}=\int \prod_{i=1}^{N} d u_{i} \prod_{i<j}\left(2 \sinh \frac{u_{i}-u_{j}}{2}\right)^{2} \exp \left(-\frac{p}{2 g_{s}} \sum_{i} u_{i}^{2}+\frac{2 \pi i}{g_{s}} \sum n_{i} u_{i}\right) \operatorname{Tr}_{R} \operatorname{diag}\left(e^{u_{i}}\right), \tag{3.6}
\end{equation*}
$$

where $\vec{n}$ is a vector of integers

$$
\begin{equation*}
\vec{n}=(\overbrace{1, \ldots, 1}^{N_{1}}, \overbrace{2, \ldots, 2}^{N_{2}}, \ldots, \overbrace{p, \ldots, p}^{N_{p}}) . \tag{3.7}
\end{equation*}
$$

The spectral curve for this matrix model can be derived [26] and it agrees with the string theory prediction [29.

For a large representation $R$ with large values of $n_{I}$ and $k_{I}$, we expect a large backreaction of fields to the Wilson loop insertion. We propose that the gauge field path-integral has now more saddle points. Each saddle point specified by $\left(N_{a}\right)$ before insertion splits into many each of which is specified by non-negative integers ( $N_{I a}$ ) satisfying the constraints

$$
\begin{equation*}
\sum_{a=1}^{p} N_{I a}=n_{I}, \quad \sum_{I=1}^{m+1} N_{I a}=N_{a} . \tag{3.8}
\end{equation*}
$$

We will argue that the contribution to the Wilson loop vev from the saddle point specified by the $\left(N_{I a}\right)$ is given by the multi-matrix model

$$
\begin{align*}
& \left\langle W_{R}\right\rangle_{p}^{\left(N_{I a}\right)}=f \prod_{I=1}^{m+1} \prod_{a=1}^{p} d_{H} u^{(I a)} \exp \left(-\frac{p}{2 g_{s}} \operatorname{Tr}\left(u^{(I a)}\right)^{2}+\left(L_{I}+\frac{2 \pi i}{g_{s}} a\right) \operatorname{Tr} u^{(I a)}\right)  \tag{3.9}\\
& \quad \times \prod_{I, a<b} \operatorname{det}\left(2 \sinh \frac{u^{(I a)} \otimes 1-1 \otimes u^{(I b)}}{2}\right)_{I<J, a, b}^{2} \prod^{\operatorname{det}}\left(2 \sinh \frac{u^{(I a)} \otimes 1-1 \otimes u^{(J b)}}{2}\right)^{2}
\end{align*}
$$

Wilson loops in the lens space matrix model have also been considered in the interesting recent work [31] and it would be of interest to apply their methods to the spectral curve in this paper.

### 3.2 Physical derivation of the matrix model

We now derive the matrix model from a D-brane configuration that realizes the Wilson loop in a lens space.

Let us recall that $X_{p}$ is a $\mathbb{Z}_{p}$ orbifold of the deformed conifold given by (2.6). The orbifold action is generated by

$$
\begin{equation*}
\left(z_{1}, z_{2}, z_{3}, z_{4}\right) \rightarrow\left(e^{-2 \pi i / p} z_{1}, e^{2 \pi i / p} z_{2}, e^{2 \pi i / p} z_{3}, e^{-2 \pi i / p} z_{4}\right), \tag{3.10}
\end{equation*}
$$

and the $\mathbb{Z}_{p}$ action on the $S^{3}$ given by $z_{2}=z_{1}^{*}, z_{4}=-z_{3}^{*}\left(\right.$ so $\left.\left|z_{3}\right|^{2}+\left|z_{1}\right|^{2}=\mu\right)$ defines the lens space $L(p, 1)=S^{3} / \mathbb{Z}_{p}$. Since the $\mathbb{Z}_{p}$ only acts on the phases, $X_{p}$ is still a fibration of $T^{2} \times \mathbb{R}$ over $\mathbb{R}^{3}$. Let us redefine $\alpha$ to be the 1-cycle corresponding to the generator of the fundamental group, and $\beta$ the 1 -cycle given by the $2 \pi$ phase rotation of $z_{3}$. We use the axes of the two cylinders (given by $z_{1} z_{2}=$ const., $z_{3} z_{4}=$ const.) and the $\operatorname{Re}(w)$ direction as the base $\mathbb{R}^{3}$. The cycle $\beta$ degenerates at $w=\mu$ and so does $\beta^{\prime} \equiv-p \alpha+\beta$ at $w=0$. The cycle $\alpha$ never degenerates.

We engineer $\mathrm{U}(N)$ Chern-Simons theory by wrapping $N$ D-branes on the $S^{3} / \mathbb{Z}_{p}$. To insert a Wilson loop along the knot $\alpha$, we consider $P$ D-branes that wrap the non-compact cycle $L=\mathbb{R}^{2} \times S^{1}$ in which $\beta$ is contractible. See figure ${ }^{6}(\mathrm{a})$. The boundary condition $\langle R|$ on the $P$ branes picks out the Wilson loop insertion in representation $R$, as explained in (5). The boundary condition induces holonomy

$$
\begin{equation*}
\oint_{\beta=p \alpha+\beta^{\prime}} \mathcal{A}=\operatorname{diag}\left(g_{s}\left(R_{i}-i+\frac{1}{2}(P+N+1)\right)\right)_{i=1}^{P} \tag{3.11}
\end{equation*}
$$

along the contractible cycle $\beta=p \alpha+\beta^{\prime}$. By fibering the $T^{2}$ over a semi-infinite line ending on the locus where $\beta^{\prime}$ degenerates, we obtain a 3 -manifold in which $\beta$ is non-contractible. We can consider a configuration of D-branes wrapping this 3 -manifold. Is the configuration equivalent to the one we started with, as in the $S^{3}$ case? We assume it is, and we will see evidence below. The basic nontrivial cycle in the new 3 -manifold is $\alpha$, and the holonomy along it is given by

$$
\begin{equation*}
\int_{\alpha} \mathcal{A}=\frac{1}{p} \operatorname{diag}\left(g_{s}\left(R_{i}-i+\frac{1}{2}(P+N+1)\right)\right)_{i=1}^{P} \tag{3.12}
\end{equation*}
$$



Figure 6: (a) The cycle $\beta$ degenerates along the vertical line while $-p \alpha+\beta$ degenerates along the other line. If a linear combination $q \alpha+r \beta$ degenerates, it does so along a line in the $(q, r)$ direction. (b) $P$ non-compact branes are distributed along the line where $-p \alpha+\beta$ degenerates. (c) There are $m+1$ copies of $S^{3} / \mathbb{Z}_{p}$.
because $\beta^{\prime}$ is contractible. See figure ${ }^{6}(\mathrm{~b})$.
As in the $S^{3}$ case, it is natural to split the $P$ non-compact branes into $m$ stacks with the $I$-th stack containing $n_{I}$ branes. We can now replace $X_{p}$ by the $\mathbb{Z}_{p}$ orbifold of the large $N$ dual geometry given by the equations (2.7). This is possible because (2.7) are invariant under the orbifold action. The non-compact branes are now replaced by compact ones wrapping copies of lens space $S^{3} / \mathbb{Z}_{p}$. Thus we reach the desired system of D-branes, whose world-volume theory is $m+1$ copies of Chern-Simons theory on lens space $S^{3} / \mathbb{Z}_{p}$, interacting via Ooguri-Vafa operators. The system is shown in figure 6 (c).

To write down the matrix model, we need to choose the vacuum of the theory. We have a $\mathrm{U}\left(n_{I}\right)$ Chern-Simons theory on the $I$-th lens space. As reviewed in the previous subsection, the theory has many vacua corresponding to the choice of a flat connection. Let us choose the vacuum specified by the partition $n_{I}=\sum_{a} N_{I a}$. Then according to the prescriptions in 10], the contribution to the Wilson loop vev from this vacuum is given by

$$
\begin{align*}
\left\langle W_{R}\right\rangle_{S^{3} / \mathbb{Z}_{p}}^{\left(N_{I a}\right)} \sim \int \prod_{I, a, i} & d_{H} u^{(I a)} \prod_{I, a<b} \operatorname{det}\left(2 \sinh \frac{u^{(I a)} \otimes 1-1 \otimes u^{(I b)}}{2}\right)^{2} \\
& \times \prod_{I<J, a, b} \operatorname{det}\left(2 \sinh \frac{\left(u^{(I a)}+a_{I} / p\right) \otimes 1-1 \otimes\left(u^{(J b)}+a_{J} / p\right)}{2}\right) \\
& \times \exp \left(-\frac{p}{2 g_{s}} \operatorname{Tr}\left(u^{(I a)}\right)^{2}+\frac{2 \pi i}{g_{s}} a \operatorname{Tr} u^{(I a)}\right) \tag{3.13}
\end{align*}
$$

By redefining the variables as $u^{(I a)} \rightarrow u^{(I a)}-g_{s} L_{I} / p=u^{(I a)}-a_{I} / p+(I$-independent $)$, we obtain (3.9). It is remarkable that we get the holonomy $a_{I} / p$, including the factor of $1 / p$, which is necessary to be consistent with the algebraic derivation. The success gives us confidence in the assumption we made above.

This brane construction makes it clear what the dual bubbling geometry should be. It should be the toric Calabi-Yau shown in figure 2(b), where all the copies of lens space
have undergone geometric transition. This proposal will be confirmed in subsection 3.4 by deriving the spectral curve of the matrix model, and showing that it is the mirror of the toric Calabi-Yau.

### 3.3 Algebraic derivation of the matrix model

The vector of integers $\vec{n}$ in (3.5) breaks the $\mathrm{U}(N)$ invariance down to the product subgroup $\times_{a} \mathrm{U}\left(N_{a}\right)$ and subsequently the $\mathcal{S}_{N}$ symmetry to $\mathcal{S}^{\prime}=\times_{a} \mathcal{S}_{N_{a}}$. Nonetheless the Wilson loop is in the representation $R$ of $\mathrm{U}(N)$ and as such we cannot immediately apply all the steps we used to solve the $S^{3}$ case in section 2.3. The workaround is to consider a generating function of matrix integrals, one term of which will correspond to the Wilson loop vev $\left\langle W_{R}\right\rangle_{p}^{\left(N_{I, a}\right)}$. This generating function will have $\mathcal{S}_{N}$ symmetry and thus we need only the technology used in section 2.3 to solve this case as well.

So we will consider the generating function with variables $z_{1}, \ldots, z_{p}$

$$
\begin{equation*}
W_{R, p}\left(z_{a}\right)=\int \frac{1}{N!} \prod_{i=1}^{N} d u_{i} \prod_{i<j}\left(2 \sinh \frac{u_{i}-u_{j}}{2}\right)^{2} e^{-\frac{p}{2 g_{s}} \sum_{i} u_{i}^{2}}\left(\prod_{i=1}^{N} \sum_{a=1}^{p} e^{\frac{2 \pi i}{g_{s}} a u_{i}} z_{a}\right) \operatorname{Tr}_{R} \operatorname{diag}\left(e^{u_{i}}\right) \tag{3.14}
\end{equation*}
$$

The coefficient of $\prod_{a} z_{a}^{N_{a}}$ in (3.14) is $\left\langle W_{R}\right\rangle_{p}$. Since all the $u_{i}$ are dummy variables on the same footing, we can straightforwardly repeat the analysis of section 2.3 to arrive at

$$
\begin{align*}
W_{R, p}\left(z_{a}\right)= & \int \prod_{I=1}^{m+1}\left(\frac{1}{n_{I}!} \prod_{i=1}^{n_{I}} d u_{i}^{(I)} \prod_{i<j}\left(2 \sinh \frac{u_{i}^{(I)}-u_{j}^{(I)}}{2}\right)^{2} e^{-\frac{p}{2 g_{s}} \sum_{i}\left(u_{i}^{(I)}\right)^{2}} e^{L_{I} \sum_{i} u_{i}^{(I)}}\right) \\
& \times \prod_{I} \prod_{i}\left(\sum_{a} e^{\frac{2 \pi i}{g_{s}} a u_{i}^{(I)}} z_{a}\right) \prod_{I<J} \prod_{i, j}\left(2 \sinh \frac{u_{i}^{(I)}-u_{j}^{(J)}}{2}\right) \tag{3.15}
\end{align*}
$$

where the eigenvalues $\left(u_{i}\right)$ have been divided into $m$ groups $\left(u_{i}^{(I)}\right)$ ( $m$ is again the number of groups of rows in $R$ ). To understand the coefficient of $\prod z_{a}^{N_{a}}$ it is best to divide up the eigenvalues $\left(u_{i}\right)$ into $\left(u_{i}^{(a)}\right)$ and also $\left(u_{i}^{(I, a)}\right)$ such that

$$
\begin{align*}
\left(u_{i}^{(I)}\right) & =\bigsqcup_{a=1}^{p}\left(u_{i}^{(I a)}\right), \quad\left(u_{i}^{(a)}\right)=\bigsqcup_{I=1}^{m+1}\left(u_{i}^{(I a)}\right) \\
\left(u_{i}\right) & =\bigsqcup_{I=1}^{m+1}\left(u_{i}^{(I)}\right)=\bigsqcup_{a=1}^{p}\left(u_{i}^{(a)}\right) \tag{3.16}
\end{align*}
$$

So clearly we have the constraints (3.8) and for each choice of non-negative integers $\left(N_{I a}\right)$ which satisfies these constraints, we have the following contribution to $\left\langle W_{R}\right\rangle_{p}$ :

$$
\begin{align*}
& \left\langle W_{R}\right\rangle_{p}^{\left(N_{I a}\right)}=\int \prod_{I}\left[\prod_{a, i} \frac{d u_{i}^{(I a)}}{N_{I a}!} \prod_{a, i<j}\left(2 \sinh \frac{u_{i}^{(I a)}-u_{j}^{(I a)}}{2}\right)^{2} \prod_{a<b, i, j}\left(2 \sinh \frac{u_{i}^{(I a)}-u_{j}^{(I b)}}{2}\right)^{2}\right.  \tag{3.17}\\
& \left.\quad \times \exp \left(-\frac{p}{2 g_{s}} \sum_{i}\left(u_{i}^{(I a)}\right)^{2}+\sum_{i}\left(L_{I}+\frac{2 \pi i}{g_{s}} a\right) u_{i}^{(I a)}\right)\right] \prod_{I<J, a, b, i, j}\left(2 \sinh \frac{u_{i}^{(I a)}-u_{j}^{(J b)}}{2}\right)
\end{align*}
$$

This is the matrix model (3.9) in the eigenvalue basis. We now solve the matrix model and derive its spectral curve.

### 3.4 Spectral curve as bubbling geometry for a Wilson loop in lens space

We now derive the spectral curve associated to (3.17) that captures the contribution of the particular vacuum specified by the integers $\left(N_{I a}\right)$. Since the gauge theory sums up such contributions, the Wilson loop is actually dual to a sum over geometries.

The equation of motion for $u_{i}^{(I a)}$ that follows from (3.17) is

$$
\begin{align*}
0= & -p u_{i}^{(I, a)}+g_{s} L_{I}+2 \pi i a+g_{s} \sum_{j \neq i} \operatorname{coth} \frac{u_{i}^{(I a)}-u_{j}^{(I a)}}{2}+g_{s} \sum_{b \neq a, i} \operatorname{coth} \frac{u_{i}^{(I a)}-u_{j}^{(I b)}}{2} \\
& +\frac{1}{2} g_{s} \sum_{J \neq I, b, i} \operatorname{coth} \frac{u_{i}^{(I a)}-u_{j}^{(J b)}}{2} \tag{3.18}
\end{align*}
$$

and so we first define several resolvents

$$
\begin{equation*}
v^{(I a)}(z)=g_{s} \sum_{i=1}^{N_{I a}} \frac{e^{u_{i}^{(I a)}}}{e^{u_{i}^{(I a)}}-e^{z}}, \quad v^{(I)}(z)=\sum_{a=1}^{p} v^{(I a)}(z), \quad v(z)=\sum_{I=1}^{m+1} v^{(I)}(z) \tag{3.19}
\end{equation*}
$$

In terms of these we can write (3.18) as an equation on the (Ia)-cut:

$$
\begin{equation*}
p z+v_{ \pm}(z)=-v_{\mp}^{(I)}(z)+g_{s}\left(\sum_{J=I}^{m} k_{J}+\sum_{J=I}^{m+1} n_{J}\right)+2 \pi i a . \tag{3.20}
\end{equation*}
$$

Following the same procedure as in section 2.4 we define some new variables ${ }^{6}$

$$
\begin{align*}
& X_{0}=Z^{p} e^{v} \\
& X_{I}=A_{I} e^{-v^{(I)}}, \quad I=1 \ldots, m+1 \tag{3.21}
\end{align*}
$$

where $Z=e^{z}, A_{I}=\exp g_{s}\left(\sum_{J=I}^{m} k_{J}+\sum_{J=I}^{m+1} n_{J}\right)$. Then the spectral curve is again given by (recalling once more that $(Y, Z)$ are $\mathbb{C}^{*}$ valued variables)

$$
\begin{equation*}
f(Y, Z)=0 \tag{3.22}
\end{equation*}
$$

where

$$
\begin{align*}
f\left(Y, X_{0}, \ldots, X_{m+1}\right) & =\prod_{j=0}^{m+2}\left(Y-X_{j}\right) \\
& =\sum_{j=0}^{m+2}(-)^{j} Y^{m+2-j} E_{j}\left(X_{0}, \ldots, X_{m+1}\right) \tag{3.23}
\end{align*}
$$

The difference with section 2.4 lies in the asymptotics of the elementary symmetric polynomials, from which we can determine their structure:

$$
\begin{align*}
E_{0}\left(X_{0}, \ldots, X_{m+1}\right) & =1, \\
E_{j}\left(X_{0}, \ldots, X_{m+1}\right) & =\sum_{i=0}^{p} a_{j, i} Z^{i} \text { for } j=1, \ldots, m+1, \\
E_{m+2}\left(X_{0}, \ldots, X_{m+1}\right) & =A_{1} \ldots A_{m+1} Z^{p} . \tag{3.24}
\end{align*}
$$

[^5]

Figure 7: (a) The vertices plot the monomials $Y^{a} Z^{b}$ in (3.22). By connecting the vertices by suitable edges, one obtains a graph that is dual to the toric web in figure 2(b). (b) The eigenvalue distribution on the cylinder. Here we chose $p=3$ for illustration.

Some coefficients are easily determined:

$$
\begin{array}{lll}
a_{j, 0}=\sum_{1 \leq I_{1}<\cdots<I_{j}} B_{I_{1}} \ldots B_{I_{j}} & \text { for } & j=1, \ldots, m+1, \\
a_{j, p}=\sum_{1 \leq J_{1}<\cdots<J_{j-1}} A_{J_{1}} \ldots A_{J_{j-1}}, & \text { for } & j=2, \ldots, m+1, \quad a_{1, p}=1
\end{array}
$$

where $B_{I}=\exp g_{s}\left(\sum_{J=I}^{m} k_{J}+\sum_{J=I+1}^{m+1} n_{J}\right)$. The remaining $a_{j, i}$ are complex structure parameters that are determined by demanding that $\oint v(z) d z=-2 \pi i g_{s} N_{I a}$ for the integral around the (Ia)-cut. We can again write down the toric fan of the bubbling Calabi-Yau geometry directly from the spectral curve by plotting the monomials $Y^{a} Z^{b}$. See figure 7 (a).

We see that this toric threefold is a daisy chain of lens spaces, and the role of the complex structure deformations of the spectral curve is to desingularize each lens space. An interesting new feature of this geometry is the presence of nontrivial four-cycles.

### 3.5 Eigenvalue distribution

As in the $S^{3}$ case, when all $g_{s} n_{I}$ and $g_{s} k_{I}$ are large, the interactions between $u^{(I)}$ and $u^{(J)}$ can be neglected. The eigenvalue distribution for each $I$ is then that of a single lens space obtained in [26]. According to [26], the eigenvalues of $u^{(I a)}$ are distributed along a cut at $\operatorname{Im}(z)=2 \pi a / p$ parallel to the real axis. See figure $7(\mathrm{~b})$. This sheet is connected to $m+1$ other sheets, each through $p$ cuts. The resulting topology is that obtained by fattening the toric web in figure 2(b).

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## A. Summary of Young tableau data

The Young tableau $R$ has $n_{I}$ rows of length $K_{I}$ such that $K_{1}>K_{2}>\ldots>K_{m}>K_{m+1} \equiv$ 0 . It also has $k_{I}$ columns of length $N_{m-I+1}$ such that $N_{1}>N_{2}>\ldots>N_{m}$. We also define $n_{m+1} \equiv N-\sum_{I=1}^{m} n_{I}, N_{0} \equiv N$, and $K_{m+1} \equiv 0$. The integers $n_{I}, k_{I}, N_{I}$, and $K_{I}$ satisfy the relations

$$
\begin{equation*}
N_{I}=\sum_{J=1}^{m-I+1} n_{J} \text { for } I=0,1, \ldots, m \tag{A.1}
\end{equation*}
$$

and

$$
\begin{equation*}
K_{I}=\sum_{J=I}^{m} k_{J} \text { for } I=1,2, \ldots, m, K_{m+1}=0 \tag{A.2}
\end{equation*}
$$

See also figure [1]. We also denote by $P$ the number of rows in $R$, so $P=N_{1}$.
Other useful sets of quantities are

$$
\begin{align*}
L_{I} & =\sum_{J=I}^{m} k_{J}-\frac{1}{2} \sum_{J=1}^{I-1} n_{J}+\frac{1}{2} \sum_{J=I+1}^{m+1} n_{J},  \tag{A.3}\\
a_{I} & =g_{s}\left(K_{I}-\left(n_{1}+\cdots+n_{I-1}+\frac{1}{2} n_{I}\right)+\frac{1}{2}(P+N)\right) \\
& =g_{s}\left(L_{I}-L_{m+1}\right), \tag{A.4}
\end{align*}
$$

and

$$
\begin{align*}
& A_{I}=\exp g_{s}\left(\sum_{J=I}^{m} k_{J}+\sum_{J=I}^{m+1} n_{J}\right),  \tag{A.5}\\
& B_{I}=\exp g_{s}\left(\sum_{J=I}^{m} k_{J}+\sum_{J=I+1}^{m+1} n_{J}\right) . \tag{A.6}
\end{align*}
$$

## B. Area of the annulus diagrams

Here we explain the identification $a_{I}=g_{s}\left(L_{I}-L_{m+1}\right)$ in subsection 2.2
The $P$ non-compact D-branes with the boundary condition $\langle R|$ has background holonomy [25] (gauge equivalent to the position relative to the $N-P$ compact branes on $S^{3}$ )

$$
\begin{equation*}
\oint_{\beta} \mathcal{A}=\operatorname{diag}\left(g_{s}\left(R_{i}-i+\frac{1}{2}(P+N+1)\right)\right)_{i=1}^{P} \tag{B.1}
\end{equation*}
$$

along the $\beta$ cycle. When we split the $P$ non-compact branes into $m$ stacks, the average value of the holonomy in the $I$-th stack is

$$
\begin{equation*}
a_{I}=g_{s}\left(K_{I}-\left(n_{1}+\cdots+n_{I-1}+\frac{1}{2} n_{I}\right)+\frac{1}{2}(P+N)\right), \quad I=1, \ldots, m \tag{B.2}
\end{equation*}
$$

Since this is the distance from the $S^{3}$, it is natural to define $a_{m+1} \equiv 0$. The parameters $a_{I}$ $(I=1, \ldots, m+1)$ are then the positions of $m+1$ copies of $S^{3}$ in the new geometry given by (2.7). $a_{I}-a_{m+1}$ is the area of the annulus between the $S^{3}$ and the $I$-th stack of noncompact branes. See figure 3 (b). Note that (B.2) can be written as $a_{I}=g_{s}\left(L_{I}-L_{m+1}\right)=$ $g_{s} L_{I}+(I$-independent $)$.

## C. Alternative matrix models for a Wilson loop in $S^{3}$

Here we discuss two alternative matrix models whose partition functions are the Wilson loop vev for Chern-Simons on $S^{3}$. The first is

$$
\begin{align*}
\left\langle W_{R}\right\rangle= & \int d_{H} u d U^{(1)} d U^{(2)} \ldots d U^{(m)} e^{-\frac{1}{2 g_{s}} \operatorname{Tr}\left(u^{2}\right)}\left(\operatorname{det} U^{(1)}\right)^{k_{m}}\left(\operatorname{det} U^{(2)}\right)^{k_{m-1}} \cdots\left(\operatorname{det} U^{(m)}\right)^{k_{1}} \\
& \times \frac{1}{\operatorname{det}\left(1-e^{u} \otimes U^{(1)-1}\right)} \frac{1}{\operatorname{det}\left(1-U^{(1)} \otimes U^{(2)-1}\right)} \cdots \frac{1}{\operatorname{det}\left(1-U^{(m-1)} \otimes U^{(m)-1}\right)} . \tag{C.1}
\end{align*}
$$

Here $U^{(I)}$ is an $N_{I} \times N_{I}$ unitary matrix. The second is

$$
\begin{align*}
\left\langle W_{R}\right\rangle=\int & d_{H} u d U^{(1)} d U^{(2)} \ldots d U^{(m)} e^{-\frac{1}{2 g_{s}} \operatorname{Tr}\left(u^{2}\right)}\left(\operatorname{det} U^{(1)}\right)^{n_{1}}\left(\operatorname{det} U^{(2)}\right)^{n_{2}} \ldots\left(\operatorname{det} U^{(m)}\right)^{n_{m}} \\
& \times \operatorname{det}\left(1+e^{u} \otimes U^{(1)-1}\right) \frac{1}{\operatorname{det}\left(1-U^{(1)} \otimes U^{(2)-1}\right)} \cdots \frac{1}{\operatorname{det}\left(1-U^{(m-1)} \otimes U^{(m)-1}\right)}, \quad(\mathrm{C} .2) \tag{C.2}
\end{align*}
$$

for which $U^{(I)}$ is a $K_{I} \times K_{I}$ unitary matrix.
These models are obtained from (2.3) by the same algebraic manipulations that led to similar multi-matrix models for $\mathcal{N}=4$ Yang-Mills in (11).

## C. 1 Physical derivation

Here we give a physical derivation of the matrix model (C.1) from a D-brane configuration.
We begin with the configuration of $N$ compact and $P=N_{1}$ non-compact D-branes (figure ${ }^{3}(\mathrm{a})$ ) that we discussed in subsection (2.2). On the non-compact branes we impose the boundary condition $\langle R|$ to picks out the Wilson loop $W_{R}$ from the annulus diagrams between the branes.

We now consider a new configuration that realizes the Wilson loop insertion. We modify the geometry and introduce another locus on which $\beta$ degenerates. By fibering the $T^{2}$ over a line interval that connects the two loci where $\beta$ degenerates, we get a cycle of topology $S^{1} \times S^{2}$. We wrap $N_{1}$ D-branes around this cycle while placing external fundamental strings in an appropriate configuration. This configuration of the fundamental strings is that they insert the Wilson loop in the one-dimensional representation $\left.A_{N_{1}}^{\otimes k_{m}} 25\right] .^{7}$ Additionally we place $N_{2}$ non-compact D-branes that end on the second locus where $\beta$ shrinks. We choose the boundary condition to be $\left\langle Q^{(2)}\right|$, where the Young tableau $Q^{(2)}$ is obtained from $R$ by removing the first $k_{m}$ columns (figure 9). The external strings and annulus diagrams from the non-compact branes insert to the $S^{1} \times S^{2}$ branes the Wilson loop

$$
\begin{equation*}
\operatorname{Tr}_{A_{N_{2}}^{\otimes k m_{m}}} e^{\oint A} \operatorname{Tr}_{Q^{(2)}} P e^{\oint A}=\operatorname{Tr}_{R} P e^{\oint A} . \tag{C.3}
\end{equation*}
$$

[^6]

Figure 8: (a) The $P=N_{1}$ non-compact D-branes in figure 3 (a) are compactified by modifying the Calabi-Yau geometry without changing the topological string amplitudes. The state $|R\rangle$ specifying the boundary condition is implemented by placing external string world-sheets that insert the Wilson loop $\operatorname{Tr}_{R} \exp \oint A$. (b) The geometry and the configuration of D-branes and non-compact string world-sheets that give rise to the multi-matrix model (C.1). Each horizontal dashed line represents D-branes wrapping a Lagrangian submanifold of topology $S^{1} \times S^{2}$. The cylinder ending on the $I$-th dashed horizontal line represents fundamental strings in a configuration that inserts a Wilson loop in the representation $A_{N_{I}}^{\otimes k_{m-I+1}}$ for $I=1, \ldots, m$.


Figure 9: A shrinking sequence of Young tableaux $R \equiv Q^{(1)} \supset Q^{(2)} \supset \ldots \supset Q^{(m)}$.

Since $S^{1} \times S^{2}$ is obtained by gluing two copies of solid torus by identifying their boundaries, the path-integral there reduces to the inner product. Thus from the annulus diagrams between the $S^{3}$ and $S^{1} \times S^{2}$, the path-integral picks out the combination that inserts the Wilson loop $W_{R}$ into $S^{3}$. See figure $8($ a).

We can repeat this process (figure (9) and show that the following configuration is equivalent to the Wilson loop insertion. The total geometry is given by the same equation (2.7) as in subsection 2.2, with one locus where $\alpha$ shrinks, and $m+1$ parallel loci where $\beta$ shrinks. $N$ D-branes wrap the original $S^{3}$. We also wrap $N_{I}$ D-branes on the $S^{1} \times S^{2}$ between the $I$-th and $(I+1)$-th loci where $\beta$ shrinks. Finally we place fundamental strings, along the $I$-th locus, that insert the Wilson loop in the representation $A_{N_{I+1}}^{\otimes k_{m-I}}$ into the $I$-th $S^{1} \times S^{2}$. See figure 8(b).

Using the prescriptions in [10], we obtain the matrix model (C.1) from this D-brane configuration. There is no Gaussian factor for the Chern-Simons on $S^{1} \times S^{2}$ since the
path-integral is simply the inner product. The external fundamental strings insert the determinant factors.

It is also easy to extend the derivation to (C.2), this time using anti-branes instead of D-branes. This explains the appearance of one determinant, rather than the inverse of it, in (C.2).

## C. 2 Solving (C.1)

Now that we know the physical origin of the matrix model (C.1), let us here solve it in the large $N$ limit. In terms of the eigenvalues, the matrix model can be written as ${ }^{8}$

$$
\begin{align*}
\left\langle W_{R}\right\rangle \propto \int \prod_{i=1}^{N} d u_{i} \prod_{I=1}^{m} & \prod_{i=1}^{N_{I}} d u_{i}^{(I)} \exp \left[-\frac{1}{2 g_{s}} \sum_{i=1}^{N} u_{i}^{2}+\sum_{I=1}^{m} k_{m-I+1} \sum_{i=1}^{N_{I}} u_{i}^{(I)}\right.  \tag{C.4}\\
& +\sum_{i<j} \log \left(\sinh \frac{u_{i}-u_{j}}{2}\right)^{2}+\sum_{I=1}^{m} \sum_{i<j} \log \left(\sinh \frac{u_{i}^{(I)}-u_{j}^{(I)}}{2}\right)^{2} \\
& \left.-\sum_{i=1}^{N} \sum_{j=1}^{N_{1}} \log \left(1-e^{u_{i}-u_{j}^{(1)}}\right)-\sum_{I=1}^{m-1} \sum_{i=1}^{N_{I}} \sum_{j=1}^{N_{I+1}} \log \left(1-e^{u_{i}^{(I)}-u_{j}^{(I+1)}}\right)\right]
\end{align*}
$$

Proceeding as in subsection 2.4, by defining the resolvents

$$
\begin{align*}
v(z) & =g_{s} \sum_{i=1}^{N} \frac{e^{u_{i}}}{e^{u_{i}}-e^{z}} \\
v^{(I)}(z) & =g_{s} \sum_{i=1}^{N_{I}} \frac{e^{u_{i}^{(I)}}}{e^{u_{i}^{(I)}}-e^{z}} \text { for } I=1, \ldots, m \tag{C.5}
\end{align*}
$$

we express the saddle point equations as

$$
\begin{equation*}
v_{ \pm}(z)+z=-v_{\mp}(z)+v^{(1)}+g_{s} n_{m+1} \tag{C.6}
\end{equation*}
$$

on the $u$-cuts and

$$
\begin{equation*}
-v^{(I-1)}(z)+v_{ \pm}^{(I)}(z)=-v_{\mp}^{(I)}(z)+v^{(I+1)}(z)+g_{s}\left(k_{m-I+1}+n_{m-I+1}\right) \tag{C.7}
\end{equation*}
$$

on the $u^{(I)}$-cuts, for $I=1, \ldots, m$. Note that we have defined $v^{(0)} \equiv v, v^{(m+1)} \equiv 0$. These equations state that the following quantities are permuted as one goes through a cut:

$$
\begin{equation*}
X_{0} \equiv e^{v+z}, \quad X_{I} \equiv A_{I} e^{-v^{(m-I+1)}+v^{(m-I+2)}} \quad \text { for } I=1, \ldots, m+1 \tag{C.8}
\end{equation*}
$$

where $A_{I}$ is the familiar quantity defined in (A.5). The asymptotic behavior of $X_{I}$ as $z \rightarrow \pm \infty$ is the same as that of $X_{I}$ in subsection 2.4. The rest of the analysis then goes exactly in the same way, leading to the spectral curve (2.23). In particular $X_{I}$ here can be identified with the quantity denoted by the same symbol there. It was found there that $X_{0}$

[^7]has $m+1$ branch cuts, while $X_{I}$ with $I=1, \ldots, m+1$ shares with $X_{0}$ just the $I$-th cut. One can now show using (C.8) that $v^{(m-I+1)}(z)$ shares with $v(z)$ the first $I$ of these cuts, and thus the $I$-th cut consists of the eigenvalues of $u, u^{(1)}, \ldots$, and $u^{(m-I+1)}$.

How do we interpret the different kinds of eigenvalues that lie along the same cut? We believe that these eigenvalues form bound states due to attractive forces, as explained in (11] for a matrix model that describes a Wilson loop in $\mathcal{N}=4$ super Yang-Mills. The $I$-th cut has $n_{I}\left(u-u^{(1)} \ldots-u^{(m-I+1)}\right)$ bound states.

## C. 3 Solving (C.2)

Let us also solve (C.2), which in terms of eigenvalues reads ${ }^{9}$

$$
\begin{array}{rl}
\left\langle W_{R}\right\rangle \propto \int \prod_{i=1}^{N} d u_{i} \prod_{I=1}^{m} \prod_{i=1}^{K_{I}} & d u_{i}^{(I)} \exp \left[-\frac{1}{2 g_{s}} \sum_{i=1}^{N} u_{i}^{2}+\sum_{I=1}^{m} n_{I} \sum_{i=1}^{K_{I}} u_{i}^{(I)}\right.  \tag{C.9}\\
& +\sum_{i<j} \log \left(\sinh \frac{u_{i}-u_{j}}{2}\right)^{2}+\sum_{I=1}^{m} \sum_{i<j} \log \left(\sinh \frac{u_{i}^{(I)}-u_{j}^{(I)}}{2}\right)^{2} \\
& \left.+\sum_{i=1}^{N} \sum_{j=1}^{K_{1}} \log \left(1-e^{u_{i}-u_{j}^{(1)}}\right)-\sum_{I=1}^{m-1} \sum_{i=1}^{K_{I}} \sum_{j=1}^{K_{I+1}} \log \left(1-e^{u_{i}^{(I)}-u_{j}^{(I+1)}}\right)\right]
\end{array}
$$

Again by defining the resolvents

$$
\begin{align*}
v(z) & =g_{s} \sum_{i=1}^{N} \frac{e^{u_{i}}}{e^{u_{i}}-e^{z}} \\
v^{(I)}(z) & =g_{s} \sum_{i=1}^{K_{I}} \frac{e^{u_{i}^{(I)}}}{e^{u_{i}^{(I)}}-e^{z}} \text { for } I=1, \ldots, m \tag{C.10}
\end{align*}
$$

the saddle point equations can be written as

$$
\begin{equation*}
(v(z)+z)_{ \pm}=\left(-v(z)-v^{(1)}(z)+g_{s}\left(N+K_{1}\right)\right)_{\mp} \tag{C.11}
\end{equation*}
$$

on the $u$-cuts,

$$
\begin{equation*}
\left(-v(z)-v^{(1)}(z)\right)_{ \pm}=\left(v^{(1)}(z)-v^{(2)}(z)-g_{s}\left(n_{1}+k_{1}\right)\right)_{\mp} \tag{C.12}
\end{equation*}
$$

on the $u^{(1)}$-cuts, and

$$
\begin{equation*}
\left(v^{(I-1)}(z)-v^{(I)}(z)\right)_{ \pm}=\left(v^{(I)}(z)-v^{(I+1)}(z)-g_{s}\left(n_{I}+k_{I}\right)\right)_{\mp} \tag{C.13}
\end{equation*}
$$

on the $u^{(I)}$-cuts for $I=2, \ldots, m$, where we defined $v^{(m+1)} \equiv 0$. From these equations we see that the following quantities are permuted as one goes through a cut:

$$
\begin{equation*}
X_{0}^{\prime} \equiv e^{v+z}, \quad X_{1}^{\prime} \equiv A_{1} e^{-v-v^{(1)}}, \quad X_{I}^{\prime} \equiv A_{I} e^{v^{(I-1)}-v^{(I)}} \quad \text { for } I=2, \ldots, m+1 \tag{C.14}
\end{equation*}
$$

[^8]where $A_{I}$ are defined in (A.5). The asymptotic behavior of $X_{I}^{\prime}$ as $z \rightarrow+\infty$ is that of $X_{I}$, but as $z \rightarrow-\infty, X_{1}^{\prime}$ behaves like $X_{m+1}$, and $X_{I}^{\prime}$ like $X_{I-1}$ for $I=2, \ldots, m+1 . X_{0}^{\prime}$ and $X_{0}$ share the same asymptotics, hence so do $E_{j}\left(X_{0}^{\prime}, \ldots, X_{m+1}^{\prime}\right)$ and $E_{j}\left(X_{0}, \ldots, X_{m+1}\right)$. One concludes that the spectral curve of this model is the one found in subsection 2.4.

What is the explanation of the difference between $X_{I}^{\prime}$ and $X_{I}$ ? The functions $X_{I}$ are all holomorphic on the zero-th sheet except on the $m+1$ cuts along the real axis. While

$$
\begin{equation*}
\left(X_{0}^{\prime}, X_{1}^{\prime}, \ldots, X_{m+1}^{\prime}\right)=\left(X_{0}, X_{1}, \ldots, X_{m+1}\right) \tag{C.15}
\end{equation*}
$$

for $\operatorname{Re}(z)$ that is positively large enough, for negatively large $\operatorname{Re}(z)$ we have

$$
\begin{equation*}
\left(X_{0}^{\prime}, X_{1}^{\prime}, X_{2}^{\prime}, \ldots, X_{m+1}^{\prime}\right)=\left(X_{0}, X_{m+1}, X_{1}, \ldots, X_{m}\right) . \tag{C.16}
\end{equation*}
$$

Thus $X_{I}^{\prime}$ are not continuous, and we believe that the discontinuities arise due to the $v^{(I)}$ cuts $(I=1, \ldots, m)$ that lie in the imaginary direction as in [1].

## D. An improved matrix model for $\mathcal{N}=4$ Yang-Mills

This appendix is targeted at readers who are interested in Wilson loops in the AdS/CFT context.

It is believed [8, 32] that the correlation functions of circular loops in $\mathcal{N}=4$ YangMills are captured by the Gaussian matrix model. The precise correspondence states in particular that

$$
\begin{equation*}
\left\langle\operatorname{Tr}_{R} P \exp \oint\left(A+\theta^{i} X^{i} d s\right)\right\rangle_{\mathrm{U}(N)}=\frac{1}{Z} \int d M \exp \left(-\frac{2 N}{\lambda} \operatorname{Tr}^{2}\right) \operatorname{Tr}_{R} e^{M} . \tag{D.1}
\end{equation*}
$$

The left-hand side is the normalized expectation value of the circular supersymmetric Wilson loop in the Yang-Mills with gauge group $\mathrm{U}(N)$. The right-hand side is normalized by using the partition function $Z$ which is the integral without the insertion of $\operatorname{Tr}_{R} e^{M}$. $d M$ is the standard hermitian matrix measure, and $\lambda=g_{\mathrm{YM}}^{2} N$ is the 't Hooft coupling. In the absence of operator insertions, the eigenvalues are distributed according to the Wigner semi-circle law in the large $N$ limit.

By applying the same algebraic manipulation as we did in subsection 2.3, we conclude that the vev of a circular Wilson loop is given by several Gaussian matrix integrals correlated by interactions:

$$
\begin{align*}
\left\langle W_{R}\right\rangle_{\mathrm{U}(N)}= & \frac{1}{Z} \int \prod_{I=1}^{g+1} d M^{(I)} e^{-\frac{2 N}{\lambda} \sum_{I} \operatorname{Tr}\left(M^{(I)}\right)^{2}} e^{K_{I} \operatorname{Tr} M^{(I)}} \prod_{I<J} \operatorname{det} \frac{\left(M^{(I)} \otimes 1-1 \otimes M^{(J)}\right)^{2}}{1-e^{-M^{(I)}} \otimes e^{M_{J}}} \\
= & \frac{1}{Z} \int \prod_{I=1}^{g+1}\left(\frac{1}{n_{I}!} \prod_{i=1}^{n_{I}} d m_{i}^{(I)} \prod_{1 \leq i<j \leq n_{I}}\left(m_{i}^{(I)}-m_{j}^{(I)}\right)^{2} e^{-\frac{2 N}{\lambda} \sum_{i}\left(m_{i}^{(I)}\right)^{2}} e^{K_{I} \sum_{i} m_{i}^{(I)}}\right) \\
& \times \prod_{1 \leq I<J \leq g+1} \prod_{i=1}^{n_{I}} \prod_{j=1}^{n_{J}} \frac{\left(m_{i}^{(I)}-m_{j}^{(J)}\right)^{2}}{1-e^{m_{j}^{(J)}-m_{i}^{(I)}}} . \tag{D.2}
\end{align*}
$$

Here $M^{(I)}$ is an $n_{I} \times n_{I}$ hermitian matrix. This is the direct analog of the second expression in (2.12). We used the symbol $g$ to denote the number of blocks in $R$ as in [4, 11], so $g=m$ in the notation of figure (1).

Using this multi-matrix model, it is remarkably easy to obtain the eigenvalue distribution and reproduce the Wilson loop vevs for the representations $R$ that are realized by a D3-brane [12, 13], D5-brane [12, 14], and bubbling geometry [11]. In particular, for an $R$ with large $g_{\mathrm{YM}}^{2} n_{I}$ and $g_{\mathrm{YM}}^{2} k_{I}$, the gravitational dual is a smooth bubbling geometry. Since $m_{i}^{(I)}$ is pulled to the right by the linear potential in (D.2) with coefficient $K_{I}, m_{i}^{(I)}$ is much larger than $m_{j}^{(J)}$ if $I<J$. Then the interaction between $M^{(I)}$ and $M^{(J)}$ can be neglected. It then follows that for each $M^{(I)}$ the eigenvalues are distributed around $\lambda K_{I} / 4 N$ according to the semicircle law with half width $\sqrt{g_{\mathrm{YM}}^{2} n_{I}}$.

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[^0]:    ${ }^{1}$ To take the limit $p \rightarrow 1$ in figure 2 , one need to apply an $\operatorname{SL}(2, \mathbb{Z})$ transformation.

[^1]:    ${ }^{2}$ Recall that $P$ is the number of rows in $R$.

[^2]:    ${ }^{3}$ The resolvents $\omega^{(I)}=g_{s} \sum_{i=1}^{n_{I}} \operatorname{coth} \frac{z-u_{i}^{(I)}}{2}$ in another natural definition are simply related to the $v^{(I)}$ as $\omega^{(I)}=g_{s} n_{I}-2 v^{(I)}$.

[^3]:    ${ }^{4}$ In the limit of large $g_{s} n_{I}$ and $g_{s} k_{I}$ (the large volume limit in the $S^{3}$ case, but not in the $S^{3} / \mathbb{Z}_{p}$ case), the difference between the GLSM algebraic coordinates 28 and our moduli is suppressed. The mirror curve of the GLSM in this limit agrees with our spectral curve including the coefficients, with the choice of internal edges in figure 4(b)

[^4]:    ${ }^{5}$ Since $u$ is the holonomy along $\alpha$, its eigenvalue distribution is different from the distribution (B.1) of holonomy $\oint_{\beta} \mathcal{A}$. In particular the eigenvalues are quantized in unit of $2 g_{s}$. It should be possible to physically explain (2.31) using the fact that the matrix model captures the Wilson loop in a non-canonical framing 10 .

[^5]:    ${ }^{6}$ Despite identical nomenclature these variables are of course unrelated to those in section 2.4.

[^6]:    ${ }^{7} A_{N_{1}}$ is the rank $N_{1}$ totally anti-symmetric representation of $\mathrm{U}\left(N_{1}\right)$ and is one-dimensional.

[^7]:    ${ }^{8}$ The quantities $u_{i}^{(I)}$ and $v^{(I)}$ in this subsection are not to be confused with the quantities denoted by the same symbols in other parts of the paper.

[^8]:    ${ }^{9}$ The quantities $u_{i}^{(I)}$ and $v^{(I)}$ in this subsection are not to be confused with the quantities denoted by the same symbols in other parts of the paper.

